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AUTOMATIC MOVABLE RAILWAY PLATFORM WITH TRAIN ARRIVAL DETECTION

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Abstract: The main aim of this project is to automate railway track pedestrian crossing without use staircase & announce the status of the arrival for platform users. In this system is also used to avoid accident problems. Because, now a days train accidents are occurring frequently in India. This project identifies the status of each train using IR transceivers and informs it to microcontroller. This project is used to avoid the train collision, thus we save the valuable human lives and losses. So this project is useful for railway departments. The recent survey from the social analytics was said that the most disadvantages in Indian railway is climbing up the overhead steps for the physically challenged people. Our proposed system mainly deals with the rectification of this disadvantage. Here we are introducing the new concept of artificial railway platform. For the successful approach we are using two sensors and for the execution we are using H-bridge and for the controlling operations we are using Arduino UNO microcontroller. When the train comes near the artificial platform, the proximity sensor senses the train and gives its output to the microcontroller. The H-bridge is used for the forward and reverse movement of the platform. When the train is far away from the artificial platform the signal sends to Microcontroller, then the output signal from the controller is send to H -Bridge. This project uses regulated 5V, 500mA power supply. 7805 three terminal voltage regulator is used for voltage regulation. Bridge type full wave rectifier is used to rectify the ac out put of secondary of 230/12V step down transformer.

INTRODUCTION TO EMBEDDED SYSTEMS

An embedded system can be defined as a computing device that does a specific focused job. Appliances such as the air-conditioner, VCD player, DVD player, printer, fax machine, mobile phone etc. are examples of embedded systems. Each of these appliances will have a processor and special hardware to meet the specific requirement of the application along with the embedded software that is executed by the processor for meeting that specific requirement. The embedded software is also called “firm ware”. The desktop/laptop computer is a general purpose computer. You can use it for a variety of applications such as

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playing games, *word* processing, accounting, software development and so on. In contrast, the software in the embedded systems is always fixed listed below:

Embedded systems do a very specific task, they cannot be programmed to do different things. . Embedded systems have very limited resources, particularly the memory. Generally, they do not have secondary storage devices such as the CDROM or the floppy disk. Embedded systems have to work against some deadlines. A specific job has to be completed within a specific time. In some embedded systems, called real-time systems, the deadlines are stringent. Missing a deadline may cause a catastrophe-loss of life or damage to property. Embedded systems are constrained for power. As many embedded systems operate through a battery, the power consumption has to be very low.

Some embedded systems have to operate in extreme environmental conditions such as very high temperatures and humidity.

PROJECT INTRODUCTION

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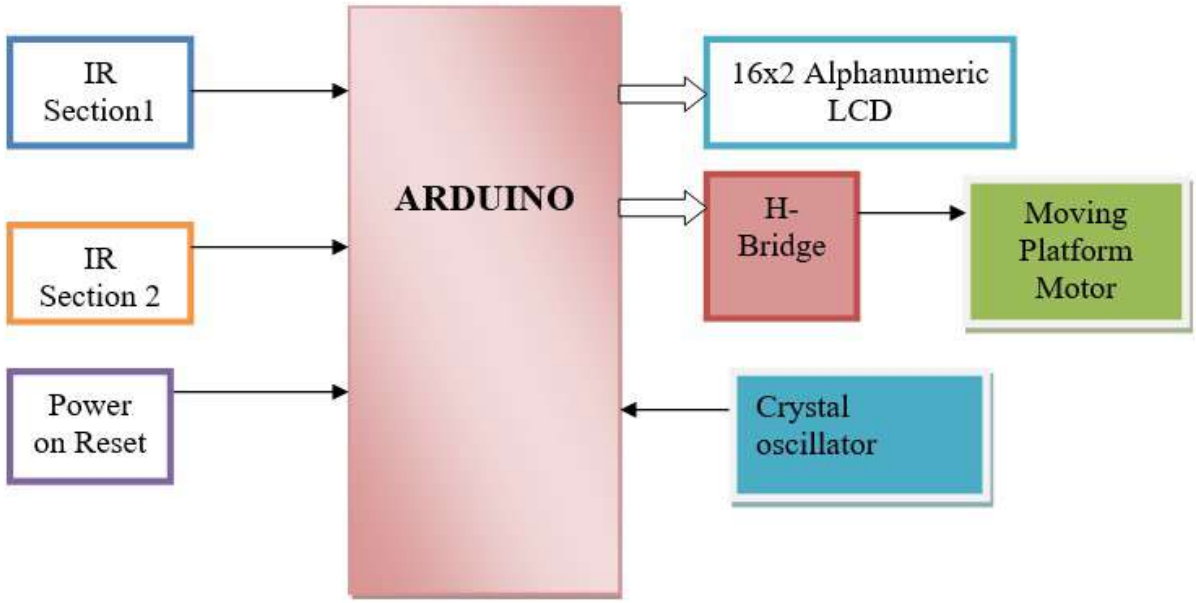
Block Diagram:



ARDUINO

Overview:

The Arduino Uno is a microcontroller board based on the ATmega328 (datasheet). It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz ceramic resonator, a USB connection, a power jack, an ICSP header, and a reset button. It contains everything needed to support the microcontroller; simply connect it to a computer with a USB cable or power it with a AC-to-DC adapter or battery to get started.

The Uno differs from all preceding boards in that it does not use the FTDI USB-to-serial driver chip. Instead, it features the Atmega16U2 (Atmega8U2 up to version R2) programmed as a USB-to-serial converter.

The Uno board has a resistor pulling the 8U2 HWB line to ground, making it easier to put into DFU mode.

The board has the following new features:

1.0 pinout: added SDA and SCL pins that are near to the AREF pin and two other new pins placed near to the RESET pin, the IOREF that allow the shields to adapt to the voltage provided from the board. In future, shields will be compatible with both the board that uses the AVR, which operates with 5V and with the Arduino Due that operates with 3.3V. The second one is a not connected pin, that is reserved for future purposes.

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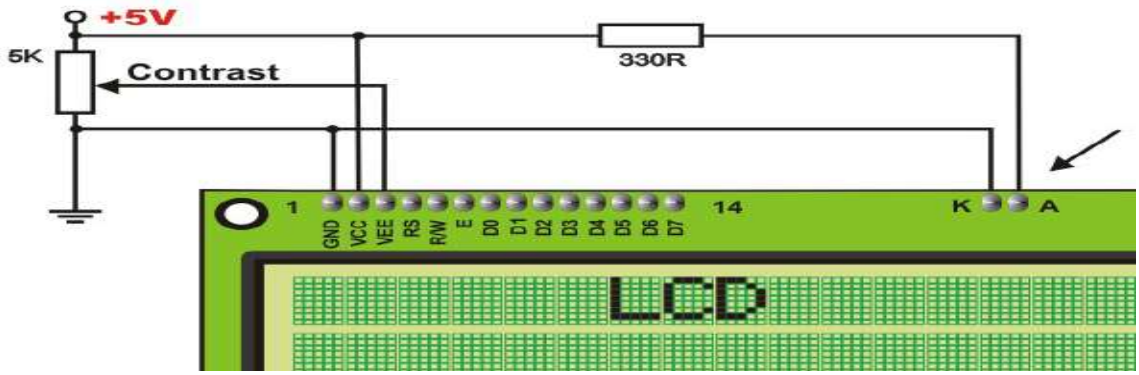
- Stronger RESET circuit.
- Atmega 16U2 replace the 8U2.

"Uno" means one in Italian and is named to mark the upcoming release of Arduino 1.0. The Uno and version 1.0 will be the reference versions of Arduino, moving forward. The Uno is the latest in a series of USB Arduino boards, and the reference model for the Arduino platform; for a comparison with previous versions, see the index of Arduino boards.

LCD screen:

LCD screen consists of two lines with 16 characters each. Each character consists of 5x7 dot matrix. Contrast on display depends on the power supply voltage and whether messages are displayed in one or two lines. For that reason, variable voltage 0-Vdd is applied on pin marked as Vee. Trimmer potentiometer is usually used for that purpose. Some versions of displays have built in backlight (blue or green diodes). When used during operating, a resistor for current limitation should be used (like with any LE diode).



IR SENSOR:

It is the same principle in ALL Infra-Red proximity sensors. The basic idea is to send infra red light through IR-LEDs, which is then reflected by any object in front of the sensor.

Then all you have to do is to pick-up the reflected IR light. For detecting the reflected IR light, we are going to use a very original technique: we are going to use another IR-LED**,** to detect the IR light that was emitted from another led of the exact same type. This is an electrical property of Light Emitting Diodes (LEDs) which is the fact that a led Produce a voltage difference across its leads when it is subjected to light. As if it was a photo-cell, but with much lower output current. In other words, the voltage generated by the leds can't be - in any way - used to generate electrical power from light, It can barely be detected. that's why as you will notice in the schematic, we are going to use a Op-Amp (operational Amplifier) to accurately detect very small voltage changes.

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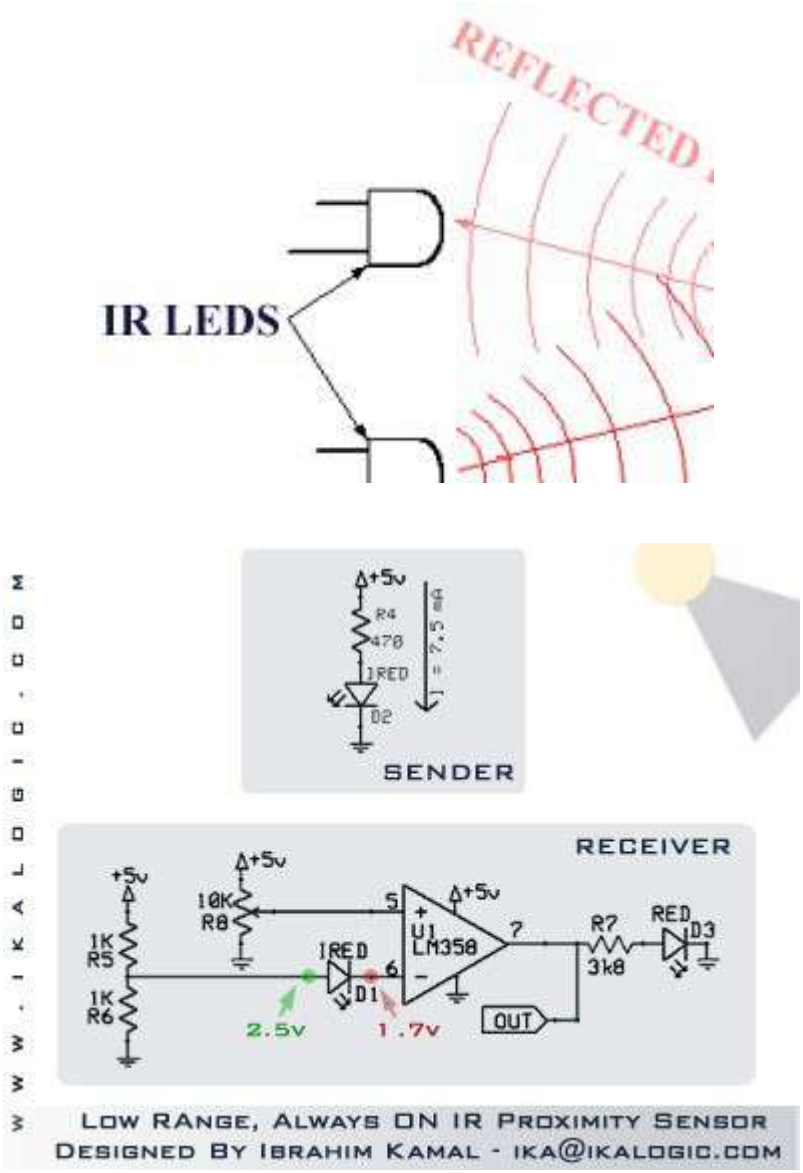

The sender is composed of an IR LED (D2) in series with a 470 Ohm resistor, yielding a forward current of 7.5mA. The receiver part is more complicated, the 2 resistors R5 and R6 form a voltage divider which provides 2.5V at the anode of the IR LED (here, this led will be used as a sensor). When IR light falls on the LED (D1), the voltage drop increases, the cathode's voltage of D1 may go as low as 1.4V or more, depending on the light intensity. This voltage drop can be detected using an Op-Amp (operational Amplifier LM358).

You will have to adjust the variable resistor (POT.) R8 so the the voltage at the positive input of the Op-Amp (pin No. 5) would be somewhere near 1.6 Volt. if you understand the functioning of Op-

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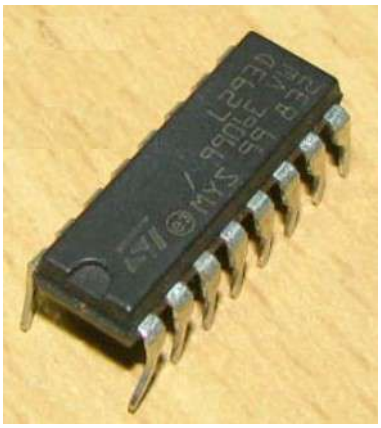
Amps, you will notice that the output will go High when the volt at the cathode of D1 drops under 1.6. So the output will be High when IR light is detected, which is the purpose of the receiver.

If the +ve input's voltage is higher than the -ve input's voltage, the output goes High (5v, given the supply voltage in the schematic), otherwise, if the +ve input's voltage is lower than the -ve input's voltage, then the output of the Op-Amp goes to Low (0V). It doesn't matter how big is the difference between the +ve and -ve inputs, even a 0.0001 volts difference will be detected, and the the output will swing to 0v or 5v according to which input has a higher voltage.

MOTOR DRIVER (L293D)

Features:



- Wide supply-voltage range: 4.5V to 36V
- Separate input- logic supply
- Internal ESD protection
- Thermal shutdown
- High-Noise-Immunity input
- Functional Replacements for SGS L293 and SGS L293D
- Output current 1A per channel (600 mA for L293D)
- Peak output current 2 A per channel (1.2 A for L293D)
- Output clamp diodes for Inductive Transient Suppression(L293D)

DESCRIPTION:

L293D is a dual H-bridge motor driver integrated circuit (IC). Motor drivers act as current amplifiers since they take a low-current control signal and provide a higher-current signal. This higher current signal is used to drive the motors.

L293D contains two inbuilt H-bridge driver circuits. In its common mode of operation, two DC motors can be driven simultaneously, both in forward and reverse direction. The motor operations of two motors can be controlled by input logic at pins 2 & 7 and 10 & 15. Input logic 00 or 11 will stop the corresponding motor. Logic 01 and 10 will rotate it in clockwise and anticlockwise directions, respectively.

Enable pins 1 and 9 (corresponding to the two motors) must be high for motors to start operating. When an enable input is high, the associated driver gets enabled. As a result, the outputs become active and work in phase with their inputs. Similarly, when the enable input is low, that driver is disabled, and their outputs are off and in the high-impedance state.

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DC MOTOR

What is DC Motor?

A DC motor is an electric motor that runs on direct current (DC) electricity. In any electric motor, operation is based on simple electromagnetism. A current-carrying conductor generates a magnetic field; when this is then placed in an external magnetic field, it will experience a force proportional to the current in the conductor, and to the strength of the external magnetic field. As you are well aware of from playing with magnets as a kid, opposite (North and South) polarities attract, while like polarities (North and North, South and South) repel. The internal configuration of a DC motor is designed to harness the magnetic interaction between a current-carrying conductor and an external magnetic field to generate rotational motion.

Let's start by looking at a simple 2-pole DC electric motor (here red represents a magnet or winding with a "North" polarization, while green represents a magnet or winding with a "South" polarization).

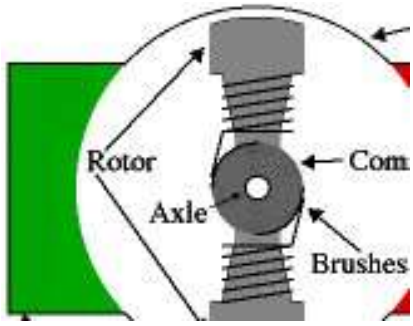

Fig.(15) DC motor

Every DC motor has six basic parts -- axle, rotor (a.k.a., armature), stator, commutator, field magnet(s), and brushes. In most common DC motors, the external magnetic field is produced by high-strength permanent magnets[1]. The stator is the stationary part of the motor -- this includes the motor casing, as well as two or more permanent magnet pole pieces. The rotor rotates with respect to the stator. The rotor consists of windings (generally on a core), the windings being electrically connected to the commutator. The above diagram shows a common motor layout -- with the rotor inside the stator (field) magnets.

SOFTWARE

Arduino software

SOFTWARE DESCRIPTION

Arduino IDE compiler:

Arduino is an open-deliver electronics platform based mostly on smooth-to-use hardware and software utility. Arduino boards can observe inputs - slight on a sensor, a finger on a button, or a Twitter message - and flip it into an output - activating a motor, turning on an LED, publishing a few components online. You could tell your board what to do by sending a hard and fast of commands to the microcontroller at the

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board. To do so that you use the Arduino programming language (based totally mostly on Wiring), and the Arduino software (IDE), based on Processing.

Over the years Arduino has been the brain of lots of obligations, from regular gadgets to complex medical gadgets. A worldwide community of makers - college students, hobbyists, artists, programmers, and specialists - has collected spherical this open-deliver platform, their contributions have brought as much as a terrific amount of available know-how that can be of terrific assist to novices and experts alike.

Arduino has become born on the Ivrea interaction format Institute as a clean tool for instant prototyping, geared towards university college students without a historic past in electronics and programming. As quickly as it reached a miles wider community, the Arduino board started converting to conform to new dreams and traumatic situations, differentiating its provide from smooth eight-bit boards to merchandise for IoT

Programs, wearable, three-d printing, and embedded environments. All Arduino boards are without a doubt open-deliver, empowering clients to assemble them independently and ultimately adapt them to their unique dreams. The software program, too, is open-supply, and its miles growing thru the contributions of customers globally.

The advantages of the Arduino IDE utility are

1. much less steeply-priced
2. The clean smooth programming surroundings
3. Extensible software program application utility and hardware

CONCLUSION

The project "**Automatic movable railway platform with train arrival detection"** been successfully designed and tested. It has been developed by integrating features of all the hardware components used. Presence of every module has been reasoned out and placed carefully thus contributing to the best working of the unit.

Secondly, using highly advanced IC's and with the help of growing technology the project has been successfully implemented.

Future scope & Aspects

- For the further development of this project we can add GPS module to the trains to monitor the movements of the trains in the same track.

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